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# ELASTIC LOADING OF HIGH PRESSURE CYLINDERS

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## SYNOPSIS

A thick-walled cylinder submitted to uniformly distributed internal and external pressures and to a uniformly distributed longitudinal load is considered.

A graphical construction is established allowing the determination of whether the material does or does not remain elastic under this state of loads, or the selection of the value of one pressure with a view to maximizing another without the cylinder undergoing plastic deformation. Three different constructions are given corresponding to the use of the criteria of Von Mises, Tresca, and of a linearized form of the intrinsic curve of Mohr-Caquot. Several remarks on the conditions and limits in the use of this method are included.

#### INTRODUCTION

*Notation.*— The letter symbols adopted for use in this paper are defined where they first appear and are listed alphabetically in the Appendix.

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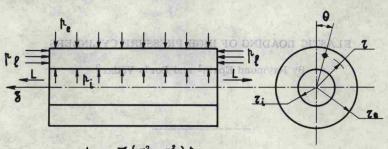
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A hollow cylinder of circular cross-section, Fig. 1, is submitted to internal, p<sub>j</sub>, external, p<sub>e</sub> and longitudinal, p<sub>1</sub> uniformly distributed pressures, and the limiting relations, i.e., the limit within which the vessel undergoes no plastic deformation between these quantities, are established. These relations will be referred to as elastic loading conditions and will be established for three criteria of plasticity:-the criteria of Von Mises,  $^3$  of Mohr-Caquot  $^4$  and of Tresca.  $^5$ 



 $L = - \Pi \left( \tau_e^2 - \tau_i^2 \right) M_{\ell}$ 

#### FIG. 1

The well-known formulas of Lamé<sup>6</sup> give the radial,  $\sigma_{r}$ , circumferential,  $\sigma_{\theta}$ , and longitudinal,  $\sigma_z$ , stresses as functions of  $p_i$ ,  $p_e$  and  $p_1$  in the following. form:

$$\sigma_{\mathbf{r}} = p_{\mathbf{i}} \frac{1}{\mathbf{k}^2 - 1} \left[ 1 - \frac{\mathbf{r}_{\mathbf{i}}^2}{\mathbf{r}^2} \mathbf{k}^2 \right] + p_{\mathbf{e}} \frac{\mathbf{k}^2}{\mathbf{k}^2 - 1} \left[ \frac{\mathbf{r}_{\mathbf{i}}^2}{\mathbf{r}^2} - 1 \right] \dots (1)$$

$$\sigma_{\theta} = p_{i} \frac{1}{k^{2} - 1} \left[ 1 + \frac{r_{i}^{2}}{r^{2}} k^{2} \right] - p_{e} \frac{k^{2}}{k^{2} - 1} \left[ \frac{r_{i}^{2}}{r^{2}} + 1 \right] \dots (2)$$

and

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Notation. - The letter symbols adopted for use in this paper are deflaced where the Appendix  $p_1 = p_1 + p_1 + p_2 + p_1 + p_2 + p_2$ 

3 Von Mises, R., "Mechanik der festen Körper im plastisch deformablen Zustand," Göttinger Nachrichten, 1913.

<sup>4</sup> Caquot, A., "Définition du domaine élastique dans les corps isotropes," Proceedings, 4th Congress of Internatl. Applied Mechanics, Cambridge, Mass., 1935, p. 24.

<sup>5</sup> Tresca, H. E., "Mémoire sur l'écoulement des corps solides," Mémoires présentés par divers savants, Vol. 18, 1868, pp. 773-799.
<sup>6</sup> Lamé, G., et Clapeyron, B. P., "Mémoires sur l'équilibre intérieur des corps solides

homogènes," Mémoires présentés par divers savants, 1833.